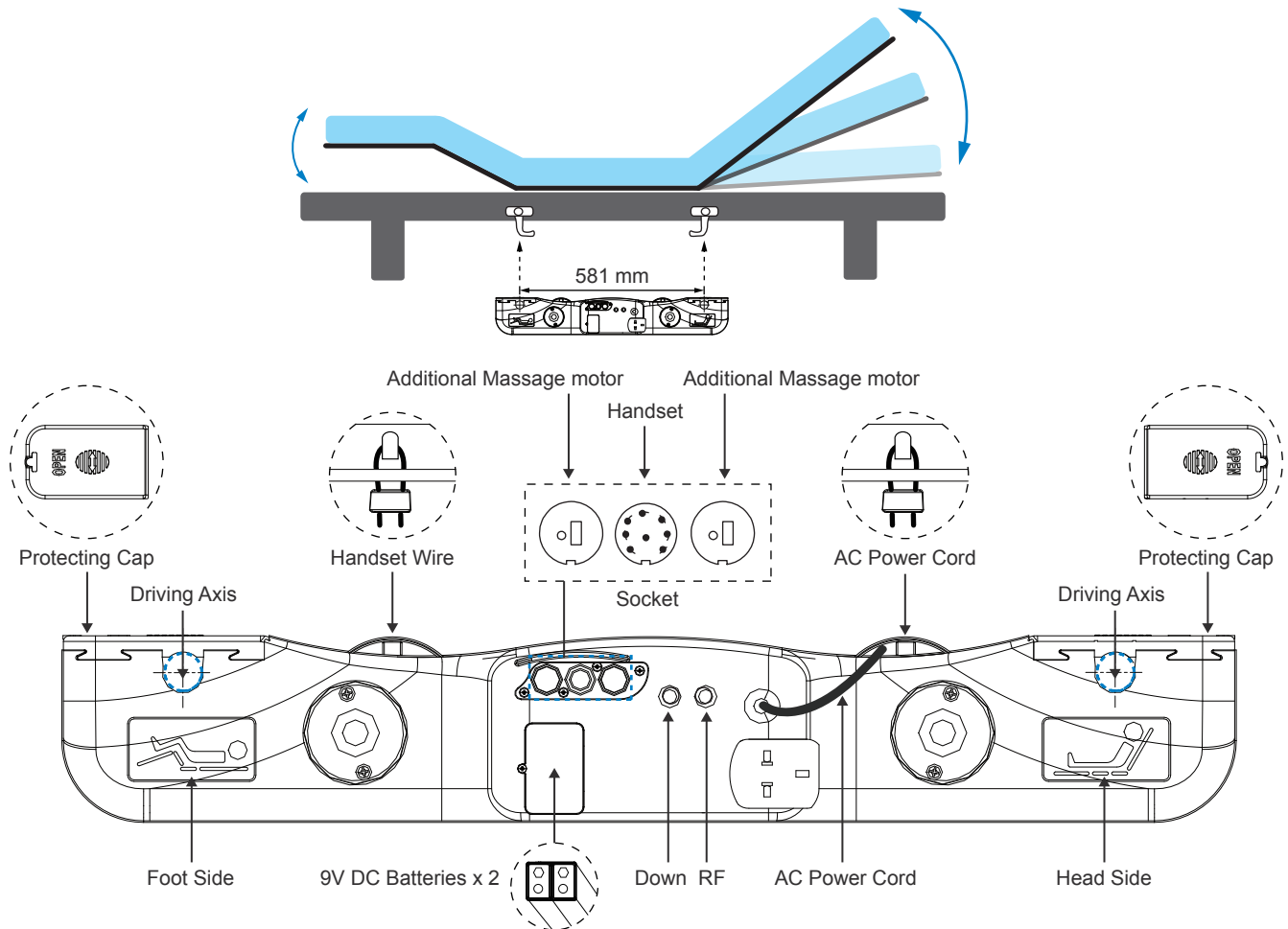





01RQ61-EN Double Motor



Installation

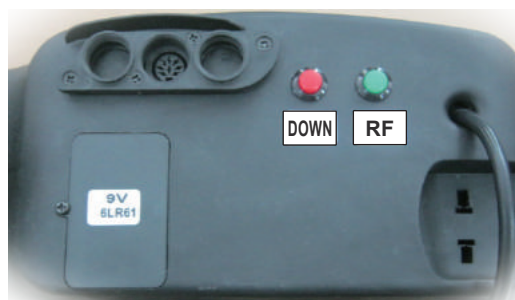
- Step 1:** Before installing, do check that the mains power cord is not plugged onto Mains power supply.
- Step 2:** Put 2 back-up batteries 9 Volts into the dedicated housing: remove the protecting cap, plug the connector onto the batteries in such a way that the wires in the upper position, then re-locate the protecting cap.
- Step 3:** Wind up the Mains power cord and the hand-set cable around the hooks (as described on the drawing) to avoid any damage during handlings.
- Step 4:** Plug the hand-set connector into the dedicated socket in the middle position.
- Step 5:** Do match the graphic symbols on the motor with the axis of the bed base:
 " Head-side " symbol must correspond to the axis linked to the back-rest mechanism,
 " Foot-side" symbol must correspond to the axis linked to the foot-rest mechanism.
- Step 6:** Before mounting the motor onto the bed base, do check out that the bed base is on horizontal position.
- Step 7:** Pull out the red tip and move along the cover enabling the holding of the bed base axis. 
- Step 8:** Make sure the piston inside is in the reset position, then mount the motor onto the axis of the bed base. Make sure they are engaged properly. 
- Step 9:** Close the cover and push back the red tips. Repeat from Step 5 for installing the other side. 
- Step 10:** Plug additional Massage motor in the socket. Make sure all the covers and parts are properly in place, plug the power cord in the Mains power supply: the motor is functional.

Operation

(Operate with 01RZG5 remote handset as example)

Pair with Remote Handset:

1. Press and hold "RF" button on the Twinmat until the buzzer beeps and relay tick (within 2 minutes).
2. Release the "RF" button on the Twinmat and press any button on the Remote handset to pair the remote handset and the RF module of the Twinmat.
3. This step is necessary when remote handset is NOT controlling the RF module or a new remote handset is used.



Emergency Lowering:

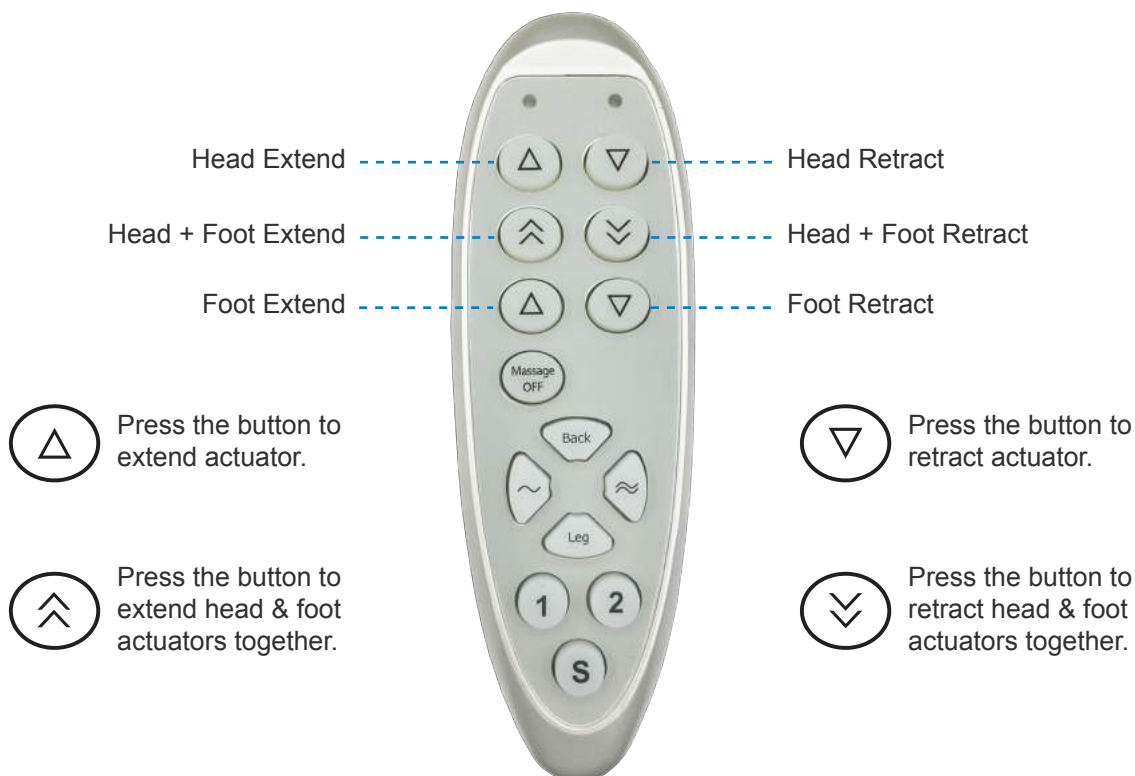
Press "Down" button on the Twinmat to lower down all the motors.

Lock Mode:

1. Press the red lock button on the back side of the remote handset to lock the buttons on the front side. The orange LED on the front side will flash 4 times to show that buttons are locked.
2. To unlock, simply press the red lock button one more time, 4 flashes of the green LED will follow to show that it's now in unlock mode.
3. Please unlock before changing batteries.



Actuator Control:



Message OFF:

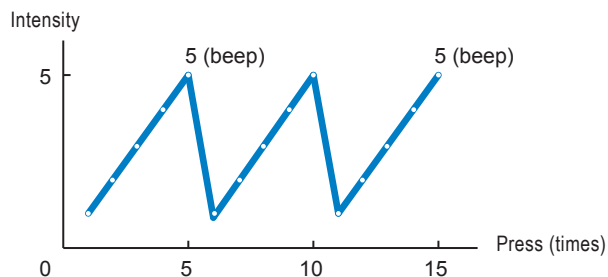


Press to stop all message motors.

Message Intensity:



1. Press once to start each motor (Default intensity is 1) for constant vibrating. Motor will off automatically after 20 min.
2. Press again to increase to next level.
3. Total 5 intensities. A buzzer will beep at 5.



Wave Mode:



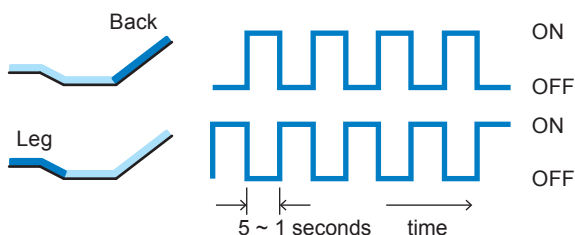
Mode 1



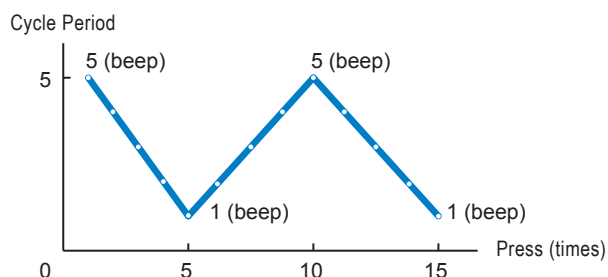
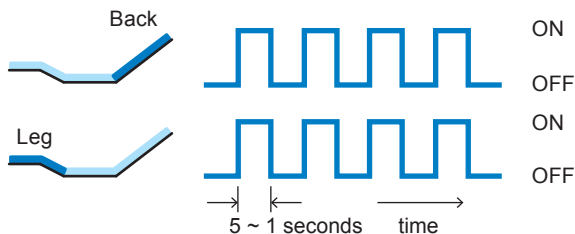
Mode 2

1. Press once to start (Default period is 5 seconds) both motors in mode 1 or 2.
2. Press again to switch to next frequency.
3. Total 5 different frequencies. A buzzer will beep at 1 (fastest).
4. Default period is not able to be changed by end-user.
5. Wave Mode 1 / 2 will start at current intensity (not default 1) if Leg and/or Back is on.

Wave Mode 1 ~



Wave Mode 2 ≈



Memory Position Setting:

1. The "1" and "2" are buttons for memory position. Make the actuator to the position where you want, push and hold button "S" for 2 seconds then push button "1" or "2", the green LED will flash which means the memory function is done.
2. The memory positions can only be over-written rather than be erased.

Execution of Memory Positions:

1. Hold the button "1" or "2", the actuator will operate to the corresponding position then stop. The green LED will flash during the operating time and then off when the actuator reaches the corresponding position.
2. When button "1" or "2" is released before the actuator reaches the corresponding position, the actuator will stop and the LED will be off.



CAUTION

- This motor is for using in slat bed bases only.
- The distance between the axes of the bed base must be 581 millimetres.
- The duty cycle for each motor is 10%, namely a continuous operating period of maximum 2 minutes, and followed by a rest period of minimum 18 minutes.
- The installation task must be carried out by qualified manpower.
- Any damage caused by mounting / dis-mounting action made by end-user shall induce a refusal of the guarantee and shall not impute to any responsibility of the manufacturer.
- Disconnect the mains power cord before removing the protecting caps and do not handle the internal parts of the motor.
- The motor is designed for indoor operating and must be kept away from humid and wet environments.
- This appliance is not intended for use by persons (including children) with reduced physical, sensory or mental capabilities, unless they have been given supervision or instruction concerning use of the appliance by a person responsible for their safety.
- If the supply cord is damaged, it must be replaced by the manufacturer, its service agent or similarly qualified persons in order to avoid a hazard.
- This device might be interfered by some other devices with same frequency (2.4 GHz; eg. WIFI router or WIFI hub). If so, please change channel from the dip switch in the battery chamber and pair the remote handset with the RF module again.